Reply from manufacturers:

Our technicians have checked the provided info and gave the following feedback:

1. From the decription, the robot's program service was re-started, which causes the camera recover its live feed camera again and again. Please try to re-flash the system image for your robot to troubleshoot the program issue.

2. For the servo on robotic arm, it seems that servo cannot be controlled. Please refer to the attached document to toubleshoot the malfunction of the servo on robotic arm.  If servos have problem, you need to replace this damaged servo.

3. If you do not have a spare servo for the damaged one, you can remove all servo cables from the expansion board, then check if the motors on chassis can operate normally.

4. If the motors still can not controlled normally, check if the power supply is sufficient. Then wait for the servo to not be controlled, connect to the robot remote system. Enter the command "sudo i2cdetect -y -a -r 1" to check IIC address. If this address cannot be found, it will be issue of either motor drive board or expansion board.

Copied the file named: “Methods to Troubleshoot ArmPi FPV Servo” in the same folder.